

Model no.: GMT-P1 -PN/EIP User's Manual

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Website: http://www.gmweighing.com

Product Performance Standards: GB/T 7724-2008



CONTENTS

| 1 General Description | 1 |
|--|-----|
| 1.1 Functions and Characteristics | . 1 |
| 1.2 Front Panel | 2 |
| 1.3 Rear Panel | . 4 |
| 1.4 Technical Specifications | 4 |
| 1.4.3 Digital: | . 5 |
| 2 Installation and Wiring | . 6 |
| 2.1 Connection of Power Supply | 6 |
| 2.2 Connection of Load Cell | 6 |
| 2.2.1 6 wires connection | 7 |
| 2.3 I/O terminals | 8 |
| 2.4 Profinet/Ethernet IP connection | 9 |
| 3 Calibration | 11 |
| 3.1 Instruction | 11 |
| 3.2 Flow Chart of Calibration | 12 |
| 3.3 Millivolt Value Display | 17 |
| 3.4 Calibration with Weights | 18 |
| 3.5 No weight calibration | 18 |
| 3.5.1 No weight zero Calibration | 18 |
| 3.5.2 No weight gain Calibration | 19 |
| Historical gain calibration | 20 |
| Sensitivity and gain calibration range | 21 |

| 22 |
|----|
| 22 |
| |
| |
| 25 |
| 27 |
| 30 |
| 32 |
| |
| 35 |
| |
| |
| 37 |
| 45 |
| |
| |
| 57 |
| 63 |
| 64 |
| 64 |
| 64 |
| 66 |
| 68 |
| |

| 9 Errors and Alarm Messages | .69 |
|---|------|
| 10. Indicator model user-defined function | . 70 |
| 11 Dimension of Indicator | .71 |



1 General Description

GMT-P1 digital indicator is specially designed for weight transmitting in industrial fields. Support PROFINET and Ethernet IP, GMT-P1 digital indicator is a small weight display which is specially designed and produced for the occasion of weight transmit industrial. The indicator has the features of compact size, stable performance, simple operation. Can be widely used in: cement mixing and asphalt mixture equipment, metallurgical blast furnace, converter and chemical industry, feed weight control and other occasions.

1.1 Functions and Characteristics

- Small volume, unique design, easy operation
- > Applicable to all kinds of resistance strain gauge bridge load cell
- Front panel numerical calibration
- Multilevel of digital filter
- Automatic zero -tracking
- Automatically zero when powered on
- PROFINET fieldbus interface
- Support Ethernet IP communication, can access Ethernet IP network
- Weight display can be remotely calibrated (remote calibration ON/OFF turned on)





1.2 Front Panel



Main Display: 6 digits, for displaying weight and the information of parameters. **Status Indicator Lamp:**

- > ZERO: Light on when present weight is within 0±1/4d. the state of 110.
- STAB: Light on when changes of weight values are within the range of motion detecting during motion detecting time.

> **NET:** Light on when indicator is in net weight status.

Keypad:



U: Zero/Esc, exit from current operation or go previous. Long press the ZERO button to calibrate the ZERO point function. The calibration range of the ZERO point in the main interface is limited by the ZERO clearing range, and cannot exceed the zeroing range, but it is not limited by

TARE

ZER

: Scroll optional values of parameter and to make flashing digit increase 1 while data inputting. Long press Tare key will proceed data transmission, and the light will be flicker, and update the F1.8 parameters

MODE

: Function selecting key, make flashing position move to the right digit when data inputting.

W/A ENTER

ENTER : Confirming Key. Confirm setting parameters or calibration and input data. Note: Under the status of gross weight, user could remove tare by pressing OPTION key, and if press Esc key in net weight mode, it will add tare weight, while it is zeroing under the status of net weight. It will show net weight value after tare, meanwhile the NET light is on.





1.3 Rear Panel



PN/EIP indicator, light on when bus communication

1.4 Technical Specifications

1.4.1 Common:

Power supply: DC24V±5% Working temperature: -10~40°C Max humidity: 90%R.H without dew



Power consumption: About 10W Dimension: 105×89×57 (mm)

1.4.2 Analog:

Load cell power: DC5V 200mA (MAX) Input impedance: 10MΩ Zero steady range: 0.00~12mV(Load cell 3mV/V) Input sensitivity: 0.01uV/d Input range: 0.00~15mV(Load cell 3mV/V) Transfer mode: Sigma - Delta A/D conversion speed: 30, 60, 120, 240, 480, 960 times/sec Non-linearity: 0.01% F.S Gain drift: 10PPM/℃ Display Precision: 1,000,000d

1.4.3 Digital:

Weight display: **6 digits red high-brightness LED** Minus display: "-" Overload display: "**OFL**" Decimal point: **5 kinds (optional)** Function keys: **4 keys soniferous keypad**



2 Installation and Wiring

2.1 Connection of Power Supply

GMT-P1 digital indicator connects DC24V power supply as follows:



Power supply connection

2.2 Connection of Load Cell

GMT-P1 digital indicator connects bridge type resistance strain gauge load cells by 6 wires or 4 wires as follows. When you use 4-wired load cells, you must bridge the SN+ with EX+ and bridge the SN- with EX-.

The signal definition of each port of the load cell connector is as follows:

EX+: Excitation+ EX-: Excitation- SN+: Sense+ SN-: Sense- SIG+: Signal+ SIG-: Signal-

| 6 wires | EX+ | SN+ | EX- | SN- | SIG+ | SIG- | Shield |
|---------|-----|-----|-----|-----|------|------|--------|
| 4 wires | EX+ | | E | X- | SIG+ | SIG- | Shield |

2.2.1 6 wires connection



Note:

1. As load cell output sensitive analog signal, please use shield cable to separate with other cables, especially AC power.

2. 4 wires connection is suitable for short distance and stable temperature or low precision field, otherwise use 6 wires connection.

3. For more load cells parallel connection, their sensitivity (mV/V) should be same.



2.3 I/O terminals



I/O tolerant definition as follows:

| Output | | | Input |
|--------|--------|-----|-----------|
| OUT1 | Stable | IN1 | Reset all |
| OUT2 | OFL | | |

Indicator input terminal connection:



Indicator input terminal connection:





2.4 Profinet/Ethernet IP connection

GMT-P1 supports **PROFINET** and **Ethernet IP** communication, and provides two Ethernet ports. With the choice of two network ports, the network port has built-in switch, which is used to realize the cascading between multiple devices.





Internal communication indicator: Hardware connection is normal, the internal communication indicator is ON.

Connector indicator: cable connection is normal, connection light is flashing

W/A

to save



3 Calibration

3.1 Instruction

- (1) Calibration procedure must be executed when a GMT-P1 indicator is put in use at the first time, the preset parameters may no longer meet the user's needs, and any part of the weighing system was changed. Position of decimal point, minimum division, maximum capacity, zero, and gain can be set and confirmed through calibration.
- (2) If you want to set only one parameter, please press

parameter's value and then press $\underbrace{\frac{ZER0}{ESC}}_{ESC}$ to exit.

(3) Please see section **3.7** for parameters' instruction.

GENERAL

(4) Please record each value in the blank table in section 3.4 during calibration for the emergency use in future.

(5) See chapter **9** for error alarm message that may be displayed during calibration.













8. The process of gain calibration is as follows. If there's no need to do gain calibration, press



GENERAL





3.3 Millivolt Value Display

This function is mainly used for system test, position-error test for weighing mechanism and linearity test for load cell.

1. System Test

(1) If display data changes with loaded weight changes, it shows that connection of load cell is correct and weighing mechanism works well.

(2)If display value is OFL (or –OFL), it means that loaded weight on load cells is too large (or too small). Please unload the weight (or load more), if display value is still OFL (or –OFL), the possible reasons are as follows:

a. There is something wrong with weighing mechanism, please check and clear.

b. The connection of load cell is incorrect, please check and clear.

c. Load cells may be damaged, please replace.

2. Position-error Test for Weighing Mechanism

Load a same weight on each corner of weighing mechanism and record displayed millivolt value respectively. If differences among these values are obvious, please adjust weighing mechanism.

3. Linearity Test for Load Cell

Load same weight for several times, and record displayed value every time. If one or two values are obviously much larger or smaller than any others, it means that the linearity of load cell is bad.



3.4 Calibration with Weights

In Chapter 3.2, steps 7 and 8 in the calibration flow chart are operation instructions of calibration zero point and calibration gain with weights

During calibration with weight, please record the zero millivolt value, gain millivolt value and the loaded weight value in the blank table below. If it is not convenient to load a weight to calibrate, these values can be used for calibration without weights.

| | Zero millivolt value(mV) | Gain millivolt value(mV) | Loaded Weight | Date | Remarks |
|---|-----------------------------|-----------------------------|------------------|------|---------|
| 1 | | | | | |
| 2 | | | | | |
| 3 | | | | | |
| 4 | | | | | |
| 5 | | | | | |

3.5 No weight calibration

3.5.1 No weight zero Calibration

When the mechanism is calibrated with weights, the millivolt value corresponding to the empty balance should be recorded. Zero calibration is accomplished by manually entering historical values.





3.5.2 No weight gain Calibration

There are two methods for weighting - free calibration gain 1) Historical calibration: Gain calibration by entering historical record values 2)Theoretical calibration: Calibrate through sensor sensitivity and maximum range value of input mechanism (the sum of the average value of input sensitivity and



maximum range when multiple sensors are connected)

Historical gain calibration



1) In gain calibration interface, press $\stackrel{\text{IARE}}{\text{OPTION}}$, and the interface displays 1. Press ENTER to enter the manual gain millivolt input interface and enter the historical millivolt value.







W/A

TARE

- 2) Press EVITER •, enter the maximum range input interface and input sensor range.
- 3) Press^{ENTER} •, complete gain calibration and enter serial port calibration switch.

3.6 Calibration Switch for Communication Interface

When calibrate the transmitter through serial port($R_S \ SP1$ or Modbus), must set to "ON" status for the calibration switch for communication interface.

3.7 Explanation for Calibration Parameters

| Symbol | Parameter | Types | Value of parameter | Default |
|--------|-----------------|-------|-------------------------------|---------|
| Pt | Decimal Point | 5 | 0 0.0 0.00 0.000 0.0000 | 0 |
| 1d | Min. Division | 6 | 1 2 5 10 20 50 | 1 |
| СР | Max. Capacity | | ≤Min. Division× 100000 | 10000 |
| t | Millivolt Value | | | |



| o | Zero | | |
|--------|--|--|--------|
| С | Gain | | |
| SIOCAL | Switch for Calibration via serial interface | | OFF |
| PASS | Password Setting | | 000000 |

Log Table for Calibration Parameters

| Parameter | Calibrated Value | Date | Remarks |
|-----------------------|------------------|------|---------|
| Decimal Point | | | |
| Min. Division | | | |
| Max. Capacity | | | |
| Load cell sensitivity | | | |
| Password | | | |



4 Working Parameters Setting

4.1 Flow Chart of Working Parameters Setting





4.2 Parameter Setting Method

GMT-P1 has 2 kinds of working parameters: Selection type and data type. For





4.3 Descriptions of Operation Parameters

| Code | Default | Description |
|------|---------|--|
| F1 | Null | The first major term of working parameter. |
| F1.1 | OFF | Switch for Auto-Zeroing when power-on, OFF: disabled ON: enabled |
| F1.2 | 0 | Zero-tracking Range $(0 \sim 9d \text{ optional})$. This parameter is for automatic calibration, disabled when is set "0". |
| F1.3 | 0 | Motion Detecting Range $(0 \sim 9d \text{ optional})$ It is stable if the change is within range. |
| F1.4 | 50 | Zeroing Range (00%~99% of Maximum capacity) |
| F1.5 | 5 | Digital filtering parameter: (1-9 as optional) 0: without filtering 9: strongest digital filtering |
| F1.6 | 0 | VF-Filter 0: without filtering 9: strongest digital filtering(1-9 as optional) |
| F1.7 | 0 | A/D conversion rate: 120,480,960,15,30,60 as optional |

| F1.8 | 0 | 0 : NET indicating net weight ; 1 : NET indicating communication |
|------|----------|--|
| F2 | Null | The second major term of working parameter. |
| F2.1 | 01 | Scale no., indicator no. |
| F2.2 | 38400 | Baud rate of serial port:1200 / 2400 / 4800 / 9600 / 19200 / 38400 / 57600 |
| F2.3 | Modbus-R | Serial ports communication mode: |
| | ти | Modbus-RTU: MODBUS RTU mode; r-Cont:SP1 continuous mode; r-SP1: SP1 command mode; tt:TOLEDOcontinuous mode; Cb920: Cb920 continuous mode。 rE-Cont:rE continuous mode; rE- rEAd:rEcommand mode; |
| F2.4 | 8-E-1 | Data format: 7-E-1: 7 data bit, even parity check, 1 stop bit; 7-O-1: 7 data bit, odd parity check, 1 stop bit; 8-E-1: 8 data bit, even parity check, 1 stop bit; 8-O-1: 8 data bit, odd parity check, 1 stop bit; |

| | | 9 n 1 9 data hita na paritu abaak 1 atan hit |
|------|---------|--|
| | | 6-II-I: 6 Uata bits, no parity check, I stop bit; |
| | | 8-n-2 : 8 data bits, no parity check, 2 stop bits; |
| F2.5 | HiLo | MODBUS dual-byte register storage turn, Hi Lo: High byte in the front, low byte at the back; Lo Hi: Low byte in the front, high byte at the back |
| F2.6 | nONE | Cont mode automatic sending time interval |
| F2.7 | 0 | tt(TOLEDO continuous mode)If send the checksum. 0: not send, 1: send. |
| F3 | Null | The third major term of working parameter. |
| F3.1 | 0-255 | The first paragraph of IP, initial vale 192 |
| F3.2 | 0-255 | The second paragraph of IP, initial vale 168 |
| F3.3 | 0-255 | The third paragraph of IP, initial vale 1 |
| F3.4 | 0-255 | The fourth paragraph of IP, initial vale 1 |
| F3.5 | 1-65534 | Modbus-TCP communication port no., initial value 502 |
| F3.6 | | Ethernet communication mode 0: b Tcp; 1: Cont |
| F4 | Null | The fourth major term of working parameter. |
| F4.1 | OFF | Parameters password setting switch. |
| F4.2 | 000000 | Parameters password setting:Valid when F4.1 is ON |
| F5 | Null | Parameter setting refer the 5 th term |

| F5.1 | 1.00000 | Weight correction factor K, weight correction factor K = Expected weight/current weight range: 0-9.99999 When the weight is calibrated (gain) or the calibration parameter is reset, the value changes to the default value of 1.00000 |
|------|---------|--|
|------|---------|--|

4.4 Set point parameters

| Code | Default | Description |
|-------|---------|---|
| P1-P4 | Null | The first term of working parameters |
| PX.1 | OFF | Change of state if need stable |
| PX.2 | 0.0 | Change of state minimum duration |
| PX.3 | P1.3=1 | Condition of validity: 0: forbid; |
| | P2.3=5 | 1: < Less than; when the weight is less than Fx. 4, the output is valid, otherwise it's invalid |
| | P3.3=0 | 2: <= Less than or equal to; when the weight is less than or |
| | P4.3=0 | equal to Fx. 4, the output is valid; otherwise, it is invalid. |
| | | 3: == Equal; when the weight is equal to Fx. 4, the output is valid; otherwise, it is invalid |



| | | 4: >=: Bigger than or equal to; when the weight is greater than Fx. 4, the output is valid, otherwise, it is invalid 5: > Bigger than; when the weight is greater than Fx. 4, the output is valid, otherwise, it is invalid 6: != not equal to; when the weight is not equal to Fx. 4, the output is valid, otherwise, it is invalid 7: _<>_ Outside the interval, When the weight is less than FX.4 or more than Fx. 5, the output is valid, otherwise, it is invalid 8: =<>= In the interval, when the weight is bigger than or equal to Fx. 4 and less than or equal to Fx. 5, the output is valid, otherwise, it is invalid 9: external trigger. If it's IO, do 1 state change for 1 trigger, if it's command, then decide according to valid or invalid command. |
|------|---|--|
| PX.4 | 0 | Set value 1; 0 ~ 999999 can be set |
| PX.5 | 0 | Set value 2; 0 ~ 999999 can be set |

Set point has 4 major terms which are user defined.


5 I/O Definition

5.1 I/O Definition

ENTER

3) Press

In the main display interface, press MODE > 4 times to display iodEF in the indicator. In this interface, press $\overset{\text{W/A}}{\bullet}$ to enter the interface of custom setting of I/O module. If the password ON/OFF of working parameter F4.1 is set as ON, the password of working parameter needs to be entered before entering the custom setting of I/O module.

Operation steps of I/O module customization: After entering the interface of I/O module customization. ENTER to modify the definition of OUT1 1) Press 2) Press OPTION A

to select the meaning code of I/O module

to confirm and return to the OUT1 interface



4) Press MODE ► to define the next I/O module, then press MODE ► to skip the current I/O module definition (keep the original definition) to set the next I/O module. The definition method is the same as the above three steps, which will not be repeated here. Press ^{XEO}/_{EC} ■ to exit when the setup is complete.

Output/Input code table:

| | Output | | | |
|-----------------------------|-------------|---|--|--|
| Code Definition Description | | | | |
| 00 | None | No definition | | |
| 01 | Stable | Effective output in stable status. | | |
| 02 | Overflow | Effective output when overflow. | | |
| O3 | Sp 1 | Effective output when set point 1 status output. | | |
| 04 | Sp 2 | Effective output when set point 2 status output. | | |

| O5 | Sp 3 | Effective output when set point 3 status output. | | |
|------|-------------|--|--|--|
| O6 | Sp 4 | Effective output when set point 4 status output. | | |
| | | Input | | |
| Code | Definitior | Description | | |
| 10 | None | No definition | | |
| 11 | Zeroing | Effective input for zeroing, pulse input signals | | |
| 12 | Sp 1 | If this signal is valid, Sp1 status will be regarded as invalid. Output valid state when comparision condition turns to invalid, and be effective again. | | |
| 13 | Sp 2 | If this signal is valid, Sp2 status will be regarded as invalid. Output valid state when comparision condition turns to invalid, and be effective again. | | |
| 14 | Sp 3 | If this signal is valid, Sp3 status will be regarded as invalid. Output valid state when comparision condition turns to invalid, and be effective again. | | |

GMT-P1 Digital Indicator



| 15 | Sp 4 | If this signal is valid, Sp4 status will be regarded as invalid. Output valid state when comparision condition turns to invalid, and be effective again. | | |
|-----|---------------|--|--|--|
| 16 | Reset all | Reset all parameter value when this signal is valid. | | |
| 17 | Tare/Add tare | Tare when the first valid signal. Add tare when second. | | |
| 18 | Tare | Tare when the signal is valid. | | |
| 19 | Add tare | Add tare when the signal is valid. | | |
| 110 | I/0 define | IO calibration lock, when I10 is defined, cannot be calibrated if the input is invalid. | | |

5.2 I/O testing











6 Communication

6.1 PROFINET Communication

GMT-P1 display has two PROFINET-IO bus connections, Port1 and Port2, and can be used as a PROFINET-IO slave station to connect to the PROFINET bus.

IP address of indicator can be set and viewed in Setup working parameters F2.1~F2.4; MAC address in F2.5~F2.10 to view.

6.1.1 I/O Status

GMT-P1 provides multi-byte, IO output in two modules, through which the master station can read and control the status of the weighing display.

Module 1: Weight and status parameter (read register)

| Weight | Parameter | Data type | Description | |
|--------|----------------------|-----------|---------------------------------|--|
| offset | | | | |
| 0 | Weight display | Dint | Current display weight, integer | |
| | Weight status marker | Duint | D4-D15 Reserved | |
| 4 | | | D3: Weight marker | |



| | | | D2: ZERO, (weight is in | |
|----|--------------------------|-------|-------------------------------------|--|
| | | | 0+/-1/4d range) | |
| | | | D1: Weight overflows bit | |
| | | | D0: Weight stable marker | |
| 8 | Gross weight | Dint | Gross weight (signal integer) | |
| 12 | Net weight | DInt | Net weight (signal integer) | |
| 16 | Tare weight | Dint | Tare weight (signal integer) | |
| 20 | Current weight | Float | Current weight, floating-point type | |
| 24 | Gross weight | Float | Gross weight, floating-point type | |
| 28 | Net weight | Float | Net weight, floating-point type | |
| 32 | Tare weight | Float | Tare weight, floating-point type | |
| 36 | Preset point status area | Word | D5-D15 Reserved | |



| | | | D3: Preset point 4 status area |
|----|-------------------------|------|--|
| | | | D2: Preset point 3 status area |
| | | | D1: Preset point 2 status area |
| | | | D0: Preset point 1 status area |
| 38 | Heartbeat communication | Word | The value of PN's communication heartbeat is always 1 after the connection is established, and the communication light is always on. After flashing the LED light, the communication light will blink at the frequency of 1Hz, and the value of communication heartbeat will also convert between 0 and 1 at the frequency of 1Hz |

Module 2: Calibration parameter (read register)

| Weight | Parameter | Data type | Description | |
|--------|--|------------|---------------------------------------|----------|
| offset | | | | |
| | Weight cali | bration | | Read |
| 0 | Weight ZERO calibration | DWord | Read absolute millivolts | register |
| 4 | Weight gain calibration | DWord | Read relative millivolts | |
| | No weight ca | alibration | | |
| 8 | No weight ZERO calibration | DWord | Read Zero calibration millivolt | |
| 12 | No weight gain calibration voltage value | DWord | Read gain calibration millivolt | |
| 16 | No weight gain calibration weight | DWord | Read gain calibration weight | |



| | Theoretical value calibration | | | |
|----|-------------------------------|-------|--|--|
| 20 | Load cell sensitivity | DWord | Load cell sensitivity | |
| 24 | Load cell full range | DWord | Load cell full range | |
| | | | | |
| 28 | Weight correction factor | DWord | used to correct the weight value factor | |
| | Custom | read | | |
| 32 | Modbus read out value DWord | | Reads the value of a specific address | |
| 36 | Modbus write status | Word | Write data return status 0: normal 1: register address is illegal 2: parameter error | |



| | | | Write data return | |
|----|--------------------|------|--------------------|--|
| | | | status 0: normal | |
| | | | 1: register | |
| | | | address is illegal | |
| 38 | Modbus read status | Word | 2: parameter error | |

Module 3: Calibration parameter (write register)

| Weight | Parameter | Data type | Description | | |
|--------|----------------------------|-----------|---|----------|--|
| offset | | | | | |
| | Weight cal | ibration | | Write | |
| 0 | Weight ZERO calibration | DWord | Write 1 to automatically calibrate zero | register | |
| 4 | Weight gain calibration | DWord | Enter weight value | | |
| | No weight calibration | | | | |
| 8 | No weight ZERO calibration | DWord | write Zero calibration | | |



| | | | millivolt |
|----|----------------------------|---------------|----------------------|
| | | | write gain |
| 40 | No weight gain calibration | Different | calibration |
| 12 | voltage value | Dword | millivolt |
| | No weight gain calibration | | write gain |
| 16 | weight | DWord | calibration weight |
| | Theoretical valu | e calibration | |
| | | | Write load cell |
| 20 | Load cell sensitivity | DWord | sensitivity |
| - | | _ | Write load cell full |
| 24 | Load cell full range | DWord | range |
| | | | |
| | | | used to correct |
| 28 | | | the weight value |
| | Weight correction factor | DWord | factor |
| | Function o | peration | |
| 32 | Function operation | Duint | D15 : I/O |



| | | module | |
|--|------|-------------|--|
| | D14 | parameter | |
| | | reset | |
| | D13 | calibration | |
| | | reset | |
| | D12 | all reset | |
| | D4-D | 011 | |
| | | reserved | |
| | D3: | GS/NT | |
| | D2: | clear tare | |
| | D1: | tare | |
| | D0: | zero | |



| Self-define write in | | | | | | | | | |
|----------------------|------------------------------|-------|---------------------------------|--|--|--|--|--|--|
| 36 | Modbus write operate address | DWord | Modbus write operate address | | | | | | |
| 40 | Modbus write operate value | DWord | Modbus write operate value | | | | | | |
| 44 | Modbus read operate value | DWord | Modbus read operate value | | | | | | |

6.1.2 Indicator Description file GSD

GMT-P1 description file and connection method can download at

www.gmweighing.com

6.1.3 Profinet master configuration GMT-P1

Taking Siemens 1200 as the master station as an example, GMT-P1 is briefly configured as the slave station.





1) Open the Botu management software and create a new project







2) Click "Add New Device" on the left and select "Controller" to select the model to use the corresponding PLC





 Double-click the PLC device in the left "Local Module", and select " Manage general station description files (GSD)" from the menu bar.

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4) Configuration network. Switch to Network View, find GMT-P1 Device, double-click add Device to connect the indicator to the PLC.

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| | |
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| CPU 1214C | GMT-P1 |
| | Not assigned |
| | |
| - | choose IO controller |
| | PLC_1. PROFINET port_1 |
| | Click"upgrouped"shows"shoose IO controller" |
| | click ungrouped shows choose to controller, |
| | choose profinet port_1 |
| | |
| | |
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GENERAL

 Set the IP address and name. In the device view, double-click the PLC module/double-click the network port to Settings





6) Assign device names. Device view as below, right-click and select assign device Name.

| Assign PROFINET dev | ice name. | | | | | |
|------------------------|----------------------|--------------------------|-----------------|---------------|-----------------------|-------------|
| - | | Configured PRO | FINET devic | e | | |
| | | PROFINET devi | te name: | mt-p1-1 | | • |
| | | Der | vice type: | MT-P1 | | 1 |
| | | Online access | | | | |
| | | Type of the PG/PC | interface: | PN/IE | | · 2 |
| | | PG/PC | interface: | Realtek PCIe | GbE Family Controller | • • • |
| 4 | | Device filter | | | | |
| • | | Only show | devices of the | same type | | |
| | | Onlyshow | devices with b | ad parameter | settings | |
| | | Only show | devices without | tnames | | |
| | | | ounces more | | | |
| | Accessible dev | vices in the network: | 1 | | | _ |
| | IP address | RC-66-41-00-27-11 | CATERONE 1 | PROFINET de | vice name Status | |
| | | 000041902711 | GMITTORET | gineprer | U OK | |
| | | 5 | | | | |
| | | 2 | | | | |
| Flash LED | | | | | | |
| | < | | | П., | | > |
| | | | | | Update list | Assign name |
| | | | | | | |
| | | | | | 3 | 4 |
| Online status informat | ion: | | | | | |
| Search complete | ted. 1 of 11 devices | were found. | | | | |
| The PROFINET d | evice name "gmt-p1 | I-1" was successfully as | signed to MAC | address "BC-6 | 6-41-90-27-11". | |
| | | | | | | |
| < | | | 11 | | | > |
| | | | | | | |
| | | | | | | Close |
| | | | | | | 2010 |



- 7) Configure indicator parameters and operate them. In the Device view, click
 "Ungrouped Device→ Parameter Modify Interface _1→ Property" on the left. Note:
 - ♦ The remote calibration ON/OFF is required to be ON to modify the

calibration parameters.

 After modifying the parameters, need to recompile and download to PLC, the parameters take effect.



| Modify Interface_1 [Para Modify Interface] | | |
|--|---|-----------|
| General IO tags System constants | Texts | |
| General Module parameters Us | er can set below paramet | ters 🗠 |
| Module paramet. | | |
| Hardware iden Select Module param | neter | |
| Select the module nee | ed | |
| modifie | d: Don't modify any modules | • |
| Basic Parameter configure | , | |
| Please Select the param w | pu | |
| want to modi | fy: Don't modify any param | • |
| Auto Clear Zero Range Who | en | |
| Clear Zero Rang | e: 50 | |
| Trace to zero rang | e: 0 | |
| Sentenced to stabilizing rang | e: 0 | |
| Digital filtering Leve | el: 5 | |
| Steady state filtering rang | e: 0 | |
| AD sampling frequence | cy: AD sampling frequency:120 | |
| Net indicator le | d: 0 | |
| remote calculator switc | h: 0 | |
| Weight Parameter configu | re | |
| Please Select the param y | ou De la califacta de la califacta | - |
| want to mode | ny: Don't moonly any param | |
| Divisio | Division 1 | |
| Full_Scal | le: 10000 | |
| SatPoint1 Parameter confi | | |
| | guie | × |
| | | |
| | | OK Cancel |

8) IO loop data operation. In the device view, view the IO address assigned to the module by the PLC. Assign I address and Q address according to IO status table. Modify corresponding parameter values by monitoring table.

| 🚻 Siemens - C:\Users\cjqin\Desktop | GMT | P1 VP | ROFI | NETIG | MT-P1VGMT-P1 | | | Ū | | | | |
|---|----------|-------|-------|-------|--------------------|---------------|----------------------------|-------------|---------|---|------------|----------------------|
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| Project tree | Ĩ | 4 | GM | T-P1 | ▶ PLC_1 [CPU 121 | 4C DC/DC/DC] | PLC tags | Default tag | table [| 34] | | |
| Devices | | | | | 1.6 | | 11 | | | | | in the second second |
| Devices | _ | | | | Απε | r assigning t | ne addresse | s needed | to vie | w and | opera | te. go online, |
| <u>1</u> | 111 | 1 | 2 | 2 | 🔿 약 🔐 and | then click*N | lonitor ⁻ to se | e the cha | anges | in thes | e valu | es. |
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| 🕶 🛅 GMT-P1 | V | • | | | Name | Data type | Address | Retain | Acces | Writa | Visibl | Monitor value |
| Add new device | | | 1 | -0 | present weight | Dint | %ID68 | | | | | -4970 |
| Devices & networks | | | 2 | -0 | weight status | UDInt | %ID72 | | | | | 9 |
| PLC_1 [CPU 1214C DC/DC/DC] | | | 3 | | Gross | DInt | %ID76 | | | | | -4970 |
| Device configuration | | | 4 | -0 | Net | DInt | %ID80 | | | | | -4970 |
| 🖳 Online & diagnostics | | | 5 | -0 | Tare | Dint | %ID84 | | | | | 0 |
| Program blocks | | | 6 | -0 | COM Heartbeat | UInt | %IW104 | | | | | 1 |
| Technology objects | | = | 7 | -0 | LC mV/V | UDInt | %ID128 | | | | | 20000 |
| External source files | | | 8 | -0 | LC Capacity | UDInt | %ID132 | | | | | 100000 |
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| 💥 Default tag table [34] | | | | | | | | | | | | |
| PLC data types | | | | | | | | | | | | |
| Watch and force tables h | eret | 0 | | | | | | | | | | |
| Image: | 3 | | | | | | | | | | | |
| Device proxy data | | | | | | | | | | | | |
| Program info | | | | | | | | | | | | |
| PLC alarm text lists | | | | | | | | | | | | |
| Local modules | ~ | | | | | | | | | | | |



 Compile, download and online. After downloading, switch to online, open the monitoring table, you can view and modify the parameters of the indicator.

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| Show all tags | | | | | 10 | cite and | | | | |
| Add new tag table | | | | | | | | | | |
| Default tag table [26] | | | | | | | | | | |
| PLC data types | | | | | | | | | | |
| Watch and force tables | | | | | | | | | | |
| Add new watch table | | | | | | | | | | |
| Gijk Force table | | | | | | | | | | |
| Online backups | | | | | Click PLC or othe | r device, | the co | mpile | butto | n |
| Device proxy data | | | | | will turn from da | rk to brid | ht | | | |
| Program info | | | | | | 1. | | | | |
| PLC alarm text lists | | | | | | | | | | |



6.2 Ethernet-IP communication

You can set and view the IP address of the indicator in the second major item of the parameter. After setting, it will take effect only after re-powering. You can also view the **MAC** address.

6.2.1 IO status

GMT-P1 provides multi-byte **IO**, through these I/O enable the master station to read and control the status of the weighing display

Module 1: weight, calibration and status parameters (read register)

| Weight | Parameter | Data type | Description |
|--------|----------------------|-----------|---------------------------------|
| offset | | | |
| 0 | Weight display | DInt | Current display weight, integer |
| | Weight status marker | Duint | D4-D31 Reserved |
| 4 | | | D3: Weight marker |
| | | | D2: ZERO, (weight is in |



| | | | 0+/-1/4d range) |
|----|--------------------------|-------|-------------------------------------|
| | | | D1: Weight overflows bit |
| | | | D0: Weight stable marker |
| 8 | Gross weight | Dint | Gross weight (signal integer) |
| 12 | Net weight | Dint | Net weight (signal integer) |
| 16 | Tare weight | Dint | Tare weight (signal integer) |
| 20 | Current weight | Float | Current weight, floating-point type |
| 24 | Gross weight | Float | Gross weight, floating-point type |
| 28 | Net weight | Float | Net weight, floating-point type |
| 32 | Tare weight | Float | Tare weight, floating-point type |
| 20 | Preset point status area | Mond | D4-D15 Reserved |
| 30 | | vvora | D3: Preset point 4 status area |



| | | | D2: Preset point 3 status area |
|----|-------------------------|------------------|---|
| | | | D1: Preset point 2 status area |
| | | | D0: Preset point 1 status area |
| 38 | Heartbeat communication | Word | The communication light flashes at 1 Hz, and the communication heartbeat switches between 0 and 1 at 1 Hz |
| | weię | ght calibration | |
| 40 | weight zero calibration | DWord | Read absolute millivolts |
| 44 | weight gain calibration | DWord | Read relative millivolts |
| | No we | ight calibration | |
| 40 | No weight zero | DWord | |
| 40 | calibration | Dvvora | Read zero calibration millivolt |

| 52 | No weight gain calibration voltage value | DWord | Read gain calibration voltage value |
|----|--|-------------------|---|
| 56 | No weight gain calibration weight value | DWord | Read gain calibration weight |
| | Theoretica | al value calibrat | ion |
| 60 | Load cell sensitivity | DWord | load cell sensitivity |
| 64 | Load cell full range | DWord | load cell full range |
| | | | |
| 68 | Weight correction factor | DWord | used to correct the weight value factor |
| | Self- | defined read | |
| 72 | Modbus read value | DWord | read specific address value |
| 74 | Modbus write status | Word | Modbus state of the write operation |



| 76 | Modbus read status | Word | Modbus state of the read operation |
|----|--------------------|------|------------------------------------|
|----|--------------------|------|------------------------------------|

Module 2: calibration and operation parameters (write register)

| Weight calibration | | | | | |
|-------------------------------|--|-------|-----------------------------|--|--|
| 0 | Weight ZERO calibration | DWord | Write 1 auto zeroing | | |
| 4 | Weight gain calibration | DWord | Write weight value | | |
| No weight calibration | | | | | |
| 8 | No weight ZERO calibration | DWord | Write Zero millivolt | | |
| 12 | No weight gain calibration voltage value | DWord | Write gain millivolt | | |
| 16 | No weight gain calibration weight | DWord | Write gain weight | | |
| Theoretical value calibration | | | | | |
| 20 | Load cell sensitivity | DWord | Write load cell sensitivity | | |

| 24 | Load cell full range | DWord | Write load cell full range | |
|--------------------|--------------------------|-------|---|--|
| | | | | |
| 28 | Weight correction factor | DWord | used to correct the weight value factor | |
| Function operation | | | | |
| | | | D15: I/O module reset | |
| | | | D14: Parameter reset | |
| | | | D13: Calibration reset | |
| | | | D12: Reset all | |
| | | | D4-D11: Reserved | |
| | | | D3: GS/NT | |
| | | | D2: Clear tare | |
| 32 | Function operation | Duint | D1: Tare | |

| | | | D0: Zero |
|----|-------------------------------|-------|-------------------------------|
| 36 | Modbus write operation | DWord | Modbus write operation |
| 40 | Modbus write operation value | Word | Modbus write operation value |
| 44 | Modbus read operation address | Word | Modbus read operation address |

6.2.2 Device description file ESD

 $\ensuremath{\textbf{GMT-P1}}$ device description file and connection method can down load at www.gmweighing.com



7 Password Input and Setting Reset

7.1 Password Input

- (1) Indicator calibration and working parameters setting default password: 000000.
- (2) User can set password in parameters when F3.1 is"ON".
- (3) When display is "PASS", need to input correct password to enter parameters.

Note:

- (2) If second input wrong, it will enter into interface for inputting password the third time

(Display change from D = z = z = z to D = z = z = z).

(3) If Input wrong for three times, main display show "Error4" and self-lock, but user can operate when power on again.

7.2 Password Setting

(1) User can set password in parameters when F3.1 is"ON".



(2) User must input same new password twice in setting password, If not same, main display show"Error"one second and return to PASS again.





7.3 Factory Reset

Note: Factory reset is only for special technicists, which will reset all of parameters and will maybe cause not working.








8 Display Testing

The following flow chart is to test lights on main-display and status lights.





9 Errors and Alarm Messages

Error ①Input error.

2 wrong data beyond parameter range.

- **Error 2** The present weight value is out of zeroing range.
- **Error 3** Scale platform is not stable when zeroing.
- Error 4 Input wrong password more than 3 times.
- Error 5 Overlimit when tare.
- **Error 6** Weight value is not stable when tare.
- OFL Weighing value is positive overflow.
- -OFL Weighing value is negative overflow.

10. Indicator model user-defined function

Long press MODE to display "LOGO" and enter the setting interface. Press ZERO to return to the setting menu

After saving, the next boot will show the newly edited model number.(ModbusTCP does not add a write function.)Add files such as "LogoSetupThread. C "and" logosetuthread. H ".

Displays character comparison table

| a. | bø | Ce | d₽ | ep | f₽ | g₽ | hø | iø | j. | \mathbf{k}_{e} | 1.0 | mø |
|------------|----|----|----|------------|----|----|----|----|------------|------------------|-----|----|
| R . | Ь. | Ε. | d. | Ε. | F. | Б. | H. | 1. | _ . | Б. | L | |
| n₽ | 00 | p₽ | q₽ | Γ ₽ | S₽ | t₽ | u. | Vé | W₽ | Xe | y₽ | Zφ |
| n. | o. | Ρ. | 9. | ٢. | 5. | ٤. | U. | U. | <u>u</u> | ۲. | Ч. | 2 |



11 Dimension of Indicator

